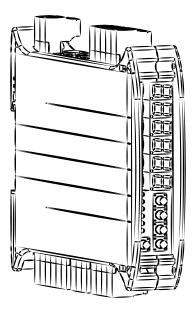


## **DGT1SP** Digital weight transmitter

**USER MANUAL** 

ENGLISH





## Introduction

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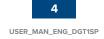
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#### Alarms



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Dear Customer,

Thank you for purchasing a DINI ARGEO product.

This manual contains all the instructions for a correct installation and commissioning of the high speed DGT1SP digital weight transmitter. While thanking you for purchasing this product, we would like to draw your attention to some aspects of this manual.

This booklet provides useful information for the correct operation and maintenance of the scale to which it refers;

it is therefore essential to pay the greatest attention to all those paragraphs that illustrate the simplest and safest way to operate.

It is recommended that you carefully follow the instructions for programming the weight transmitter; performing actions not indicated in this manual could compromise the proper functioning of the scale.

The utmost care has been taken in compiling this manual, but reports of any inaccuracies are always welcome.

The transmitter is covered by warranty and MUST NOT BE TAMPERED WITH BY THE USER under any circumstances. Any attempt at repair or modification may expose the user to the danger of electric shock and voids any warranty conditions, relieving the Manufacturer from all liability.

Any problem with the product must be reported to the manufacturer or to the retailer where it was purchased. In any case, always TURN OFF THE POWER SUPPLY before any installation or repair operation.







#### Installation requirements

Observe the following conditions for correct installation of the transmitter and of the load receiver:

- Flat, level support surface.
- Stability and absence of vibrations.
- Absence of aggressive dusts and vapours.
- Absence of draughts.
- Make sure that the platform is levelled or that the load cells are evenly supported.
- Moderate temperature and humidity (15°C 30°C and 40% 70%).
- Do not install in an environment where there is a risk of explosion.
- All transmitter connections must be made in accordance with applicable regulations in the area and environment of installation. Observe the electrical precautions listed in the section "Electrical precautions".
- Ensure that it is correctly earthed, see the relevant section "Earthing of the system".
- Do not perform welding when the load cells have already been installed.
- If necessary, use watertight sheaths and fittings to protect the load cell cables.
- Any junction boxes must be watertight.
- Anything not expressly described in this manual constitutes improper use of the equipment.





## **Electrical precautions**

- Use a regulated mains supply within  $\pm\,10\%$  of the rated voltage.
- The electrical protections (fuses, etc.) are the responsibility of the installer.
- Observe the recommended minimum distances between cables of different categories (see table on page 10).
- The following cables must comply with the maximum permissible lengths (see table on page 10), they must be shielded and must be inserted alone in metal conduits or pipes:
  - the load cell extension cables;
  - the signal amplifier cables;
  - the cables for connecting the serial ports;
  - the analog output cables.
- The cell or amplifier cables must have an independent input in the electrical panel. They must be connected (if possible) directly to the terminal block of the transmitter without passing through the conduit with other cables.
- Fit "RC" filters:
  - on the contactor coils;
  - on the solenoid valve coils;
  - on all devices that produce electrical interference.
- If condensation can occur inside the weight transmitter, it is advisable to keep the equipment powered at all times.
- Connections to load cells and any external device must be as short as possible.
- The cable ends (connectors, leads, terminals, etc.) must be installed correctly; the cable shielding must be kept intact until close to the connection point.
- If the transmitter is placed inside an electrical panel, a shielded cable must also be used for the power supply.







#### RECOMMENDED DISTANCES AND CABLE CLASSIFICATION

	Category I	Categ	gory II	Cate	gory III	Category IV
Distance	≥ 100 ≥ 200 ≥ 500	) mm	+	) mm ) mm	≥ 500	O mm
Classification	Fieldbus, LAN network (PROFIBUS, Ethernet, Devicenet). Shielded data cables (RS232). Shielded cables for analog digital signals < 25 V (sensors, load cells). Low voltage power sup- ply cables (< 60 V). Coaxial cables.	DC supply ca voltage > 60 400 V. AC supply ca voltage > 25 400 V.	) V and < ables with	Power sup with voltag Telephone	e > 400 V.	Any cable subject to lightning danger.

#### MAXIMUM ALLOWED LENGTHS

Load cell	RS232	RS485	Analog output
50 metres with 6 x 0.25 mm <sup>2</sup> cable; 100 metres with 6 x 0.5 mm <sup>2</sup> cable.	15 m with baud rate up to 19200.	1200 m with shielded 2 x 24 AWG twisted pair with outer braid + aluminium strip.	CURRENT: 100 metres with $2 \times 0.25 \text{ mm}^2$ cable; 150 metres with $2 \times 0.5 \text{ mm}^2$ cable; 300 metres with $2 \times 1 \text{ mm}^2$ cable. VOLTAGE: 50 metres with $2 \times 0.25 \text{ mm}^2$ cable; 75 metres with $2 \times 0.5 \text{ mm}^2$ cable; 150 metres with $2 \times 1 \text{ mm}^2$ cable.





## Earthing of the system

For correct earthing and optimal system operation, the transmitter, load cells, junction box, if any, and weighing structure must be earthed.

#### TRANSMITTER

The earth connection must be made via the appropriate terminal. The cable cross-section must be less than 2.5 mm<sup>2</sup>.

#### LOAD CELLS AND JUNCTION BOX

The connection must be made by connecting the earth cables to the earth bar (cables that must have a cross-section of at least 16 mm<sup>2</sup>); finally, connect the earth bar to the earth post with a cable having a cross-section of at least 50 mm<sup>2</sup>.

#### EXAMPLES:

- If more load cells are connected to the transmitter through a junction box, the cable shield from the transmitter and the cell cable shields
  must be connected to the earth socket of the junction box (refer to the junction box manual) and the junction box must be earthed using
  a copper cable with a cross-section of not less than 16 mm<sup>2</sup>.
- If the load cell is connected directly to the transmitter (without using the junction box), the cell cable shields must be connected to the earthing point (or earth bar).
- If the weighing system involves large and/or outdoor structures (weighbridges, silos, etc.) and the distance between the junction box and the weight transmitter is greater than 10 m, connect the cell cable shields to the earth socket in the junction box.

#### WEIGHING STRUCTURE

Earth the weighing structure and/or any unconnected structures (e.g. silos that release material onto the weighing structure) using cables with a cross-section of not less than 16 mm<sup>2</sup>.

Also connect the upper part with the lower part of each cell by means of a copper braid with a cross-section not less than 16 mm<sup>2</sup> (refer to the earthing examples on page 12 and page 13).

#### SERIAL CABLES AND CONNECTED INSTRUMENTS

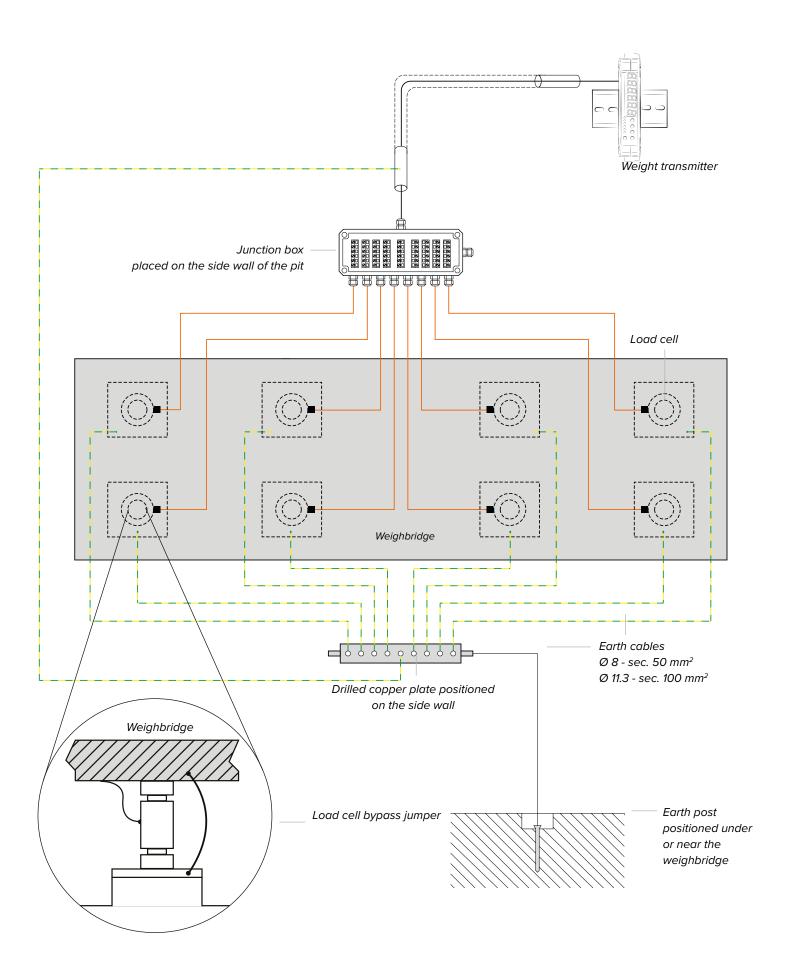
Connect the serial cable shield to the earthing point (or earth bar) inside the panel. To avoid any undesired effects, the earth reference of the connection cable, power supply and transmitter must be at the same potential.

#### **GENERAL NOTES:**

- All earth cables must be of suitable length, so as to obtain an overall resistance of the earthing system of less than 1  $\Omega$ .
- If the weighing system involves large and/or outdoor structures (weighbridges, silos, etc.):
  - the earth connection must be made by connecting the earth cables to an earth bar and the earth bar to the earth post with a cable having a cross-section of not less than 50 mm<sup>2</sup>;
  - the thickness of the cables must be greater (50 mm<sup>2</sup> instead of 16 mm<sup>2</sup> and 100 mm<sup>2</sup> instead of 50 mm<sup>2</sup>), because the voltages at stake are greater (e.g. lightning);
  - the earth post must be placed at a distance of at least 10 m from the structure.
- If the load receiver is more than 10 m from the transmitter, we recommend using the SENSE line and load cells equipped with a (SENSE) compensation circuit.

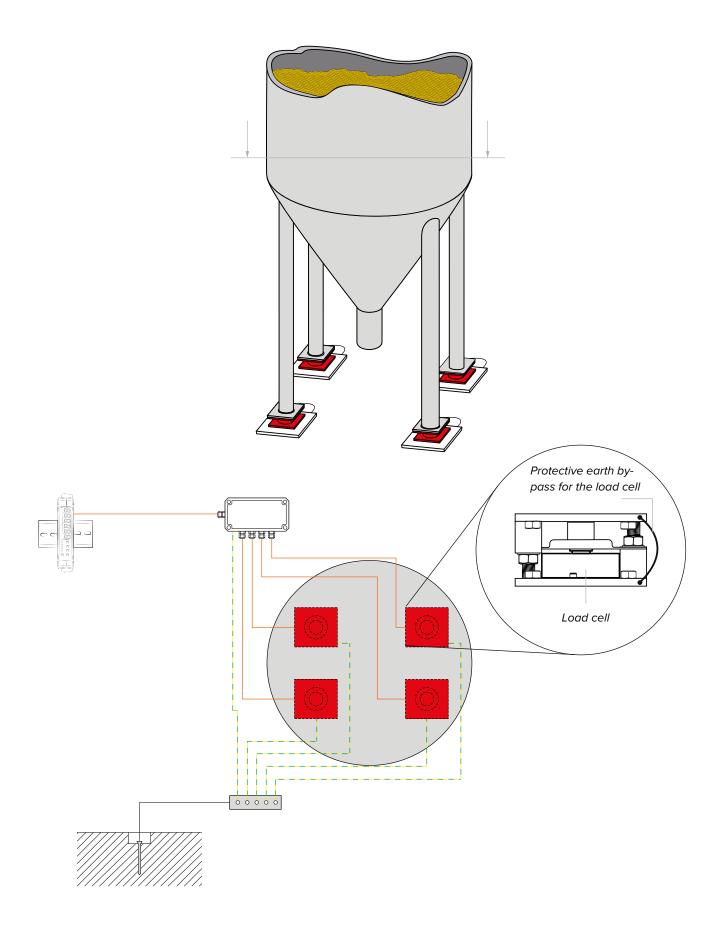








**a** 🗘







## **Technical features**

POWER SUPPLY	12 - 24 Vdc LPS or with class 2 power supply.
MAXIMUM ABSORPTION (without load cells)	DGT1SP: 1 W DGT1SP-AN: 2 W DGT1SP-PB: 2 W DGT1SP-ETHIP, DGT1SP-PRONET, DGT1SP-ETHCAT, DGT1SP-MODTCP: 4 W DGT1SP-COPEN, DGT1SP-DEVNET: 4 W
OPERATING TEMPERATURE	From -10°C to +40°C.
DISPLAY DIVISIONS	10000e, $2 \times 3000e$ for legal weighing, expandable up to 800,000 for internal use (with a minimum cell signal of 1.6 mV/V).
CONVERSION SPEED	Up to 4800 conv. / sec with single channel.
MINIMUM VOLTAGE PER DIVISION	0.3 $\mu$ V (approved transmitter); 0.03 $\mu$ V (non-approved transmitter).
COUNTING RESOLUTION	1,500,000 points (with input signal 3 mV/V).
DISPLAY	6 digits, h 8 mm (0.3").
SIGNALS	6 status indicator LED lights.
KEYPAD	mechanical with 5 keys.
TARE FUNCTION	Subtraction possible over the entire range.
LOAD CELL POWER SUPPLY	5 Vdc, 250 mA.
LOAD CELL CONNECTION	6 wires or 4 wires.
CONNECTABLE CELLS	Up to 16 350 Ω cells.
CASE	Made of plastic (ABS), suitable for DIN rail mounting (EN 60715 - DIN43880) or wall mounting.
SERIAL OUTPUTS	<ul> <li>1 half duplex RS485 bidirectional port on terminal (versions DGT1SP, DGT1SP-AN).</li> <li>1 PROFIBUS port on DB9 connector (DGT1SP-PB* version);</li> <li>2 ETHERNET ports (versions DGT1SP-ETHIP*, DGT1SP-MODTCP*, DGT1SP-ETHCAT*, DGT1SP-PRONET*);</li> <li>1 CANOPEN port on 5-pole terminal (DGT1SP-CANOP* version);</li> <li>1 DEVICENET port on 5-pole terminal (DGT1SP-DEVNET* version).</li> <li>1 USB port (micro USB type B) → Virtual COM (Device).</li> <li>* Fieldbus models are not equipped with port 485.</li> </ul>
OUTPUTS / INPUTS	<ul> <li>4 photomosfet NO or NC outputs: max 60 Vdc 0.5 A max / 48 Vac 0.5A;</li> <li>2 configurable inputs (bidirectional optocouplers): 12 - 48 Vdc;</li> <li>Input reading and output update time: 1 msec;</li> <li>16-bit analog output (DGT1SP-AN version).</li> <li>Current: 0 - 20 mA / 4 - 20 mA. Voltage: 0 - 5 Vdc, 0 - 10 Vdc.</li> <li>The maximum applicable resistance on the current output is 300 Ω while the minimum applicable resistance on the voltage output is 1 kΩ.</li> </ul>
LOAD CELL SENSITIVITY	Maximum sensitivity of the connectable load cells: 6 mV/V.
FIELDBUS UPDATE RATES	Up to 120 Hz.
CERTIFICATIONS	Indicated on the EC Declaration of Conformity of the product.



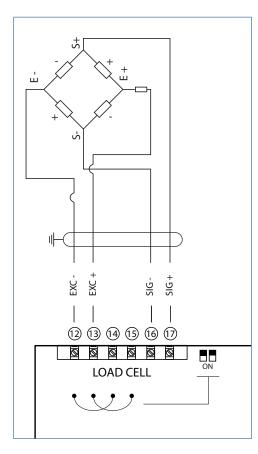


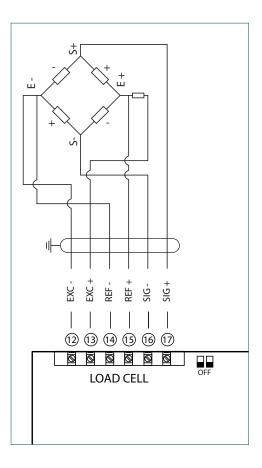
## Load cell installation

After carrying out the instructions for the platform or load receiver, the shielded cable from the cell must be properly connected to the terminal block of the transmitter (see section "Wiring diagrams").

The transmitter has one channel for 6-wire connection to load cells (using the REFERENCE).

The REFERENCE allows you to compensate for any voltage drop on the section of cable connecting the transmitter to the load receiver. It is especially useful when the distance between the transmitter and the load receiver is more than 10 metres, or in high-resolution applications.





**4-WIRE CONNECTION** 

**4-WIRE CONNECTION** 

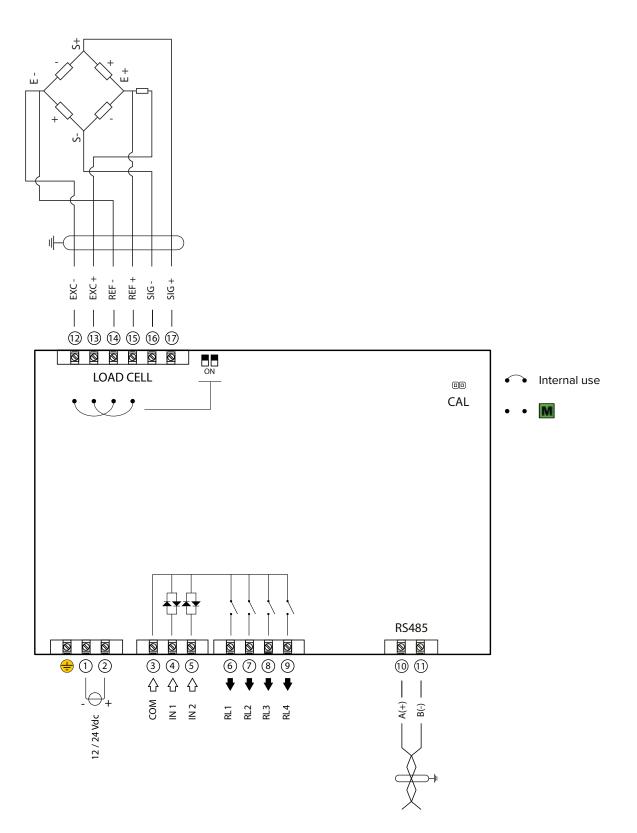






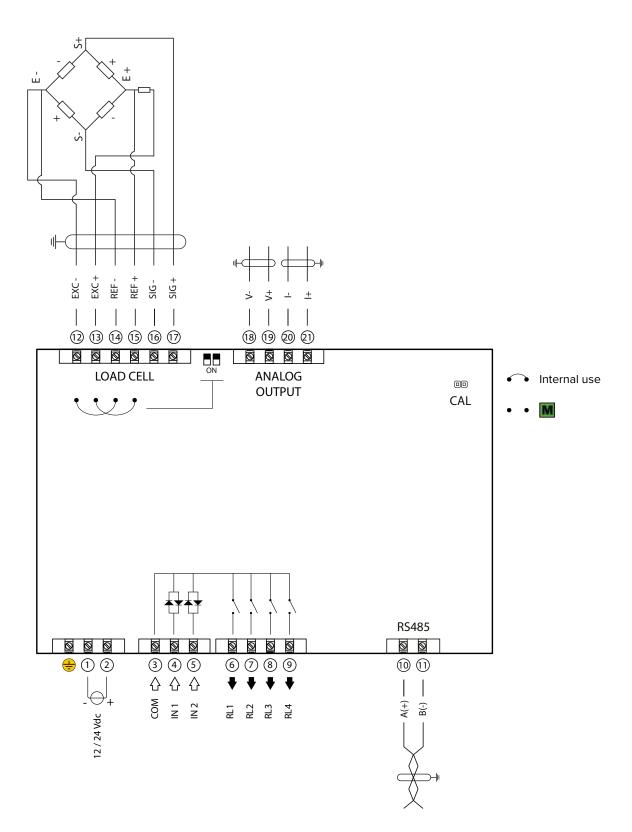
#### **DGT1SP**

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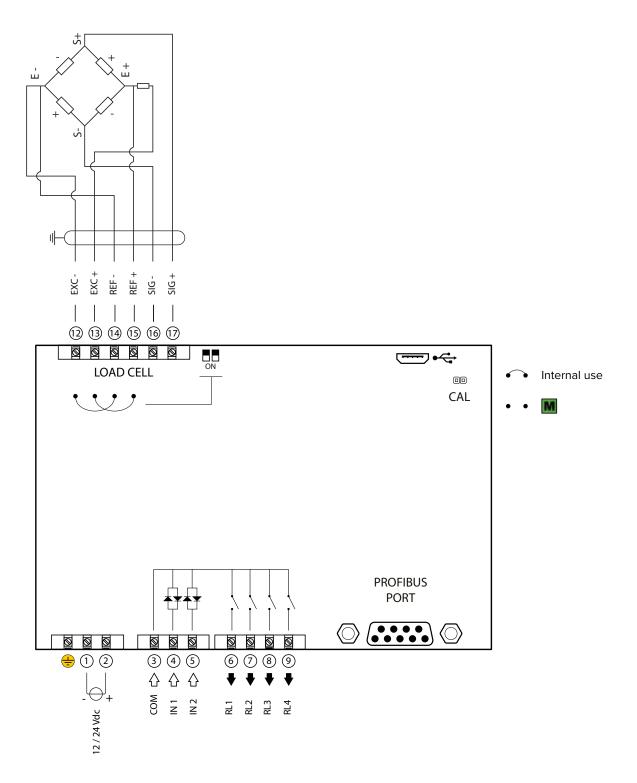


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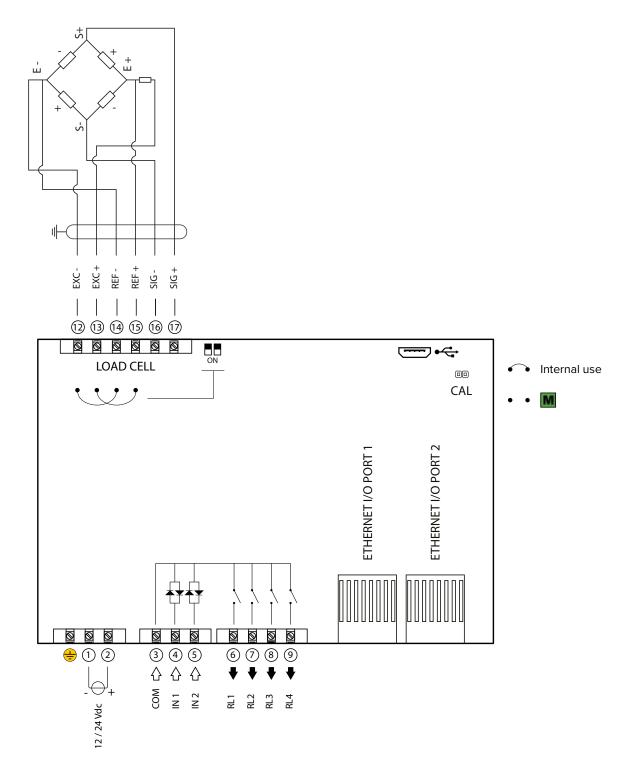


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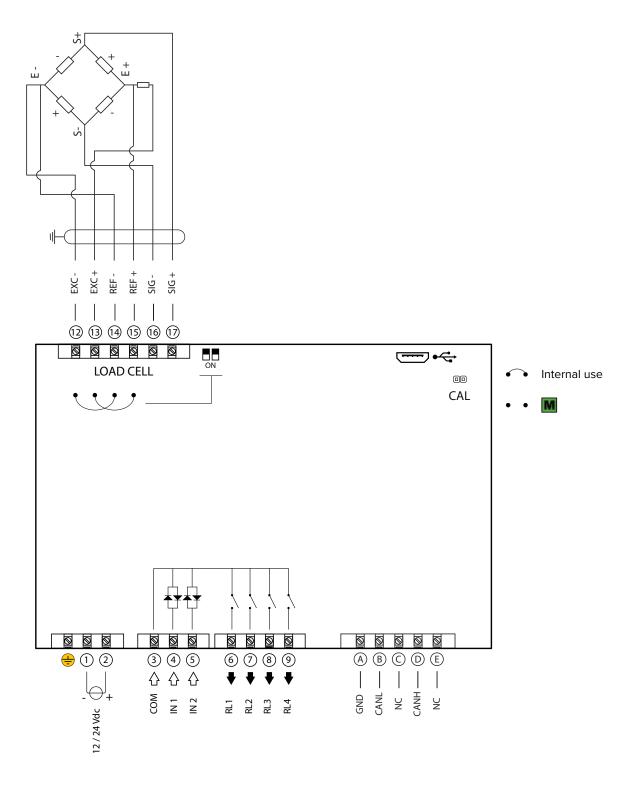


## DGT1SP-ETHIP, DGT1SP-ETHCAT, DGT1SP-PRONET, DGT1SP-MODTCP





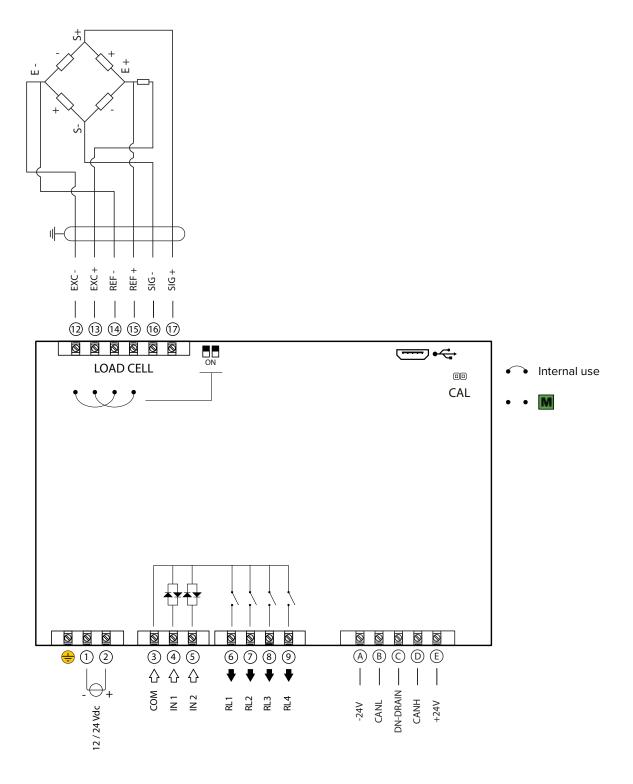






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#### **DGT1SP-DEVNET**

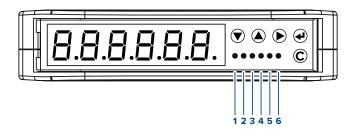






21



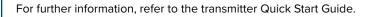


Symbol	Description		Number	Description
•	Semi-automatic zeroing.         Decreases the selected digit.         Semi-automatic tare.         Increases the selected digit.		1	Gross weight on zero.
			2	Unstable weight.
	Activates the function. Selects the digit to be changed.		3	A tare is active.
			4	A special function is active.
4	Confirms a value. Prints / Transmits data.		5	Output 1 is active.
С	Reboots the transmitter.		6	Output 2 is active.

#### Quick menu

The transmitter is equipped with a quick menu, through which you can program the main parameters of the scale. To enter the quick menu, follow the procedure below:

- **1.** Reboot the transmitter.
- 2. Press the key when the display shows 888888.





The advanced menu contains all the transmitter configuration parameters for the most advanced adjustments.

## Access to the advanced menu and saving the changes

**1.** Reboot the transmitter.

Press the key when the display shows 888888.

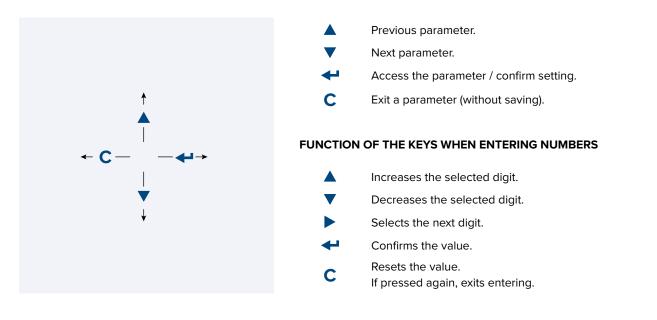
f

#### HOW TO EXIT THE SETUP AND SAVE CHANGES

1. Press C several times, until the display shows "SAUE?".

Press + to save or C to exit without saving.

#### Function of the keys in the menu



In the menu description on the following pages the  $\bigvee$  symbol indicates repeated pressing of the  $\checkmark$  key until the parameter indicated is reached.



Indicates repeated pressing of the key.



Parameter visible only under certain conditions.

Parameter or menu subject to approval.

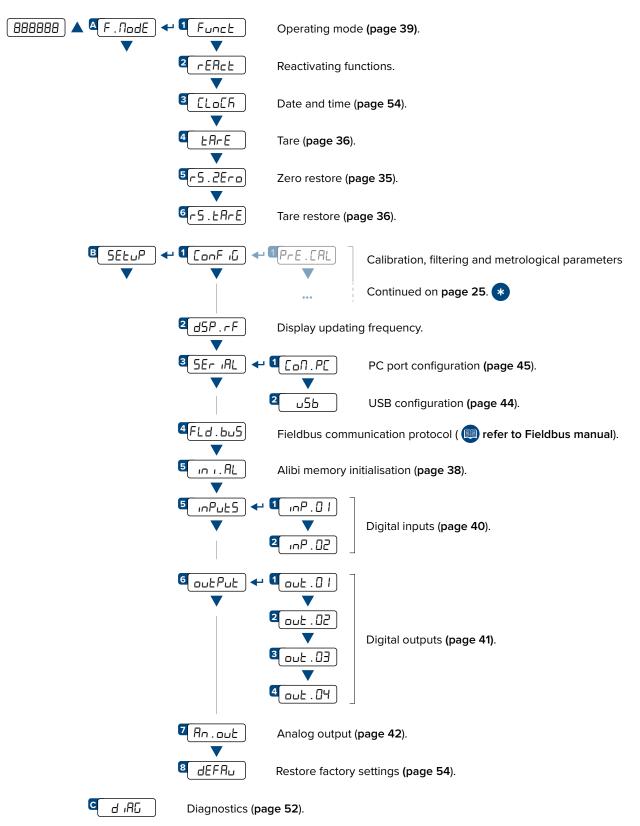
Default value of the parameter.







#### Block diagram of the menu





Complete menu on pages **24 - 25** 



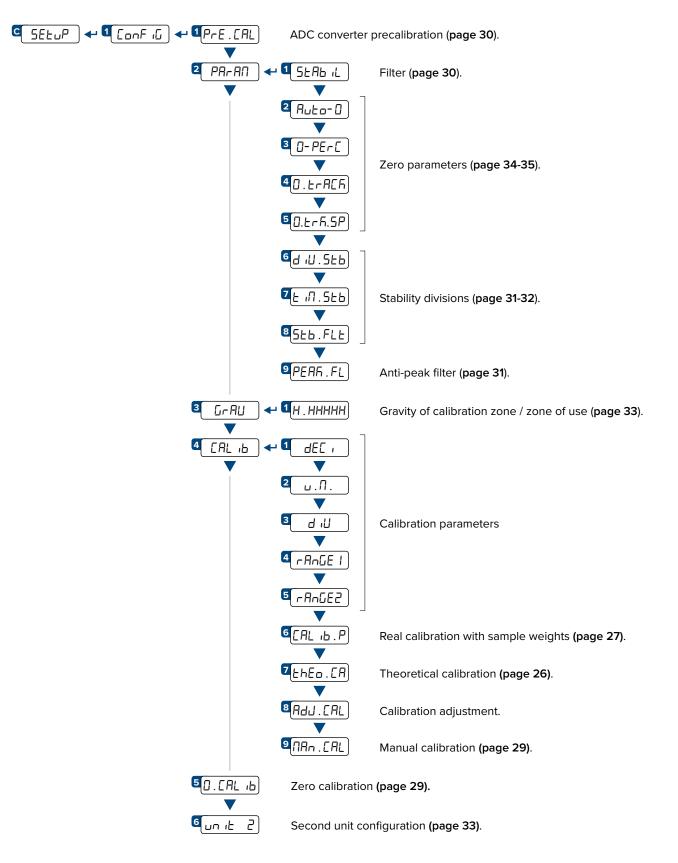
Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the ← key to confirm.



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LEGEND:

the 💙 key.

Indicates repeated pressing of

25

Parameter or menu subject

to approval.

Ö

Parameter visible only

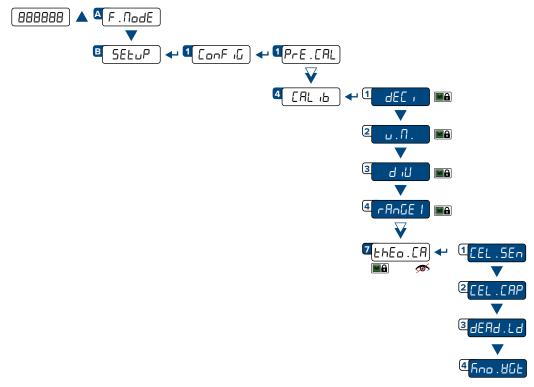
under certain conditions.

Ø



Default value of the parameter.

#### **Theoretical calibration**



#### CALIBRATION PROCEDURE:

1. Set the calibration parameters:

- dEC = Number of decimals.
- $\Box . \Pi$ . = Unit of measurement ( $F_{\Box}, \Box, L, Lb$ ).
- d ו = Minimum division.
- \_A∩GE I = Maximum range.

#### 2. Set the cell data:

- $5E_n$ . [EL = Cell sensitivity (given by the average mV/V value of cells).
- *LEL* . *LRP* = Total capacity of the cells (given by the sum of the capacities of each cell).

3. Enter the weight value of the structure in the dERd.Ld parameter. If you do not know this value, enter "0".

4. If the structure contains a quantity of material whose weight value is known (e.g. full silo), enter this value in the hop . Hot parameter.

#### 5. Application of theoretical calibration:

Press the C key to exit the calibration menu. The display shows Eh ERLP. Press the rest key to confirm the use of the theoretical calibration, or the C key to cancel.



Complete menu on pages 24 - 25

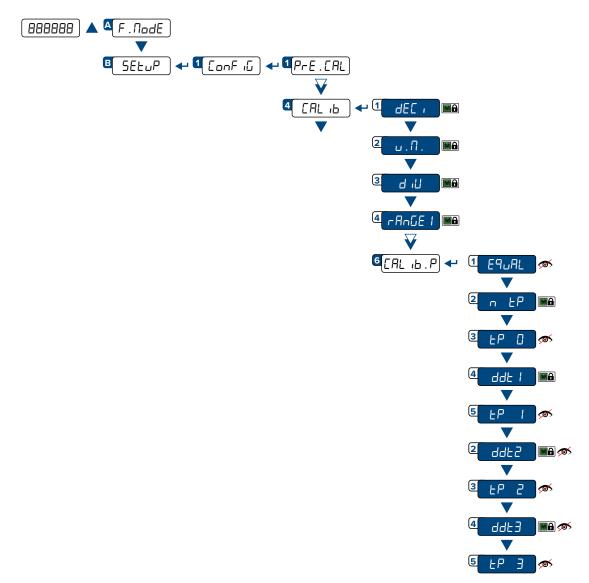


Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the **4** key to confirm.



## **Calibration with sample weights**



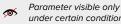
#### CALIBRATION PROCEDURE:

**1.** Set the calibration parameters:

- dEC i = Number of decimals.
  - υ.П. = Unit of measurement ( $F_{L}$ , L, L, L).
  - ы п = Minimum division.
  - -AnGE I = Maximum range.
- 2. Acquire the calibration points (continued on next page)

#### LEGEND:

Indicates repeated pressing of the 💙 key.



under certain conditions.

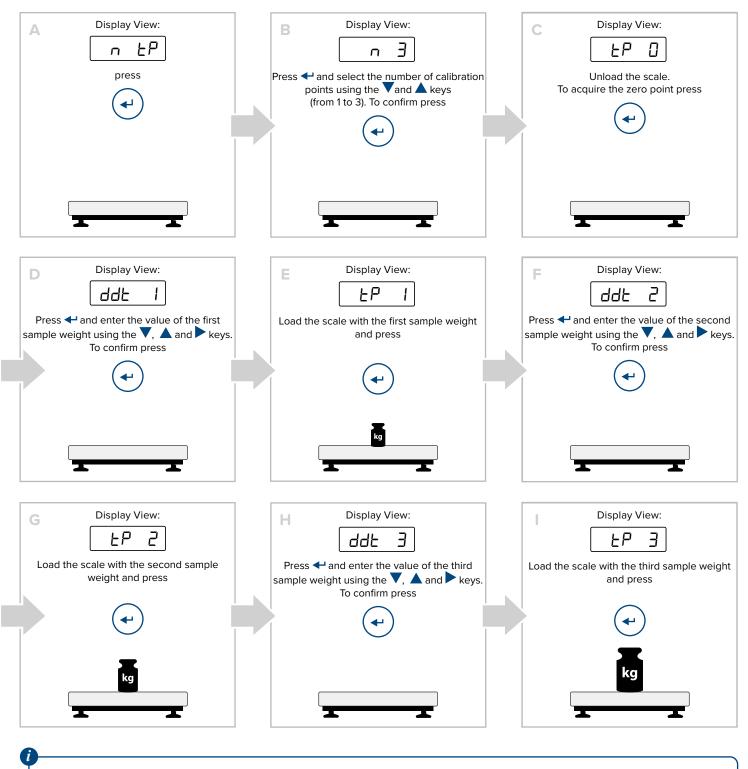
Parameter or menu subject to approval.



27



#### 3. Acquire the calibration points:



For successful calibration, the value of the largest sample weight must be at least 50% of the capacity.



Complete menu on pages 24 - 25 MENU ACCESS:

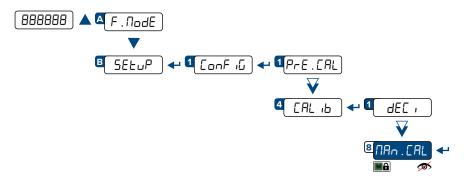
Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the ← key to confirm.



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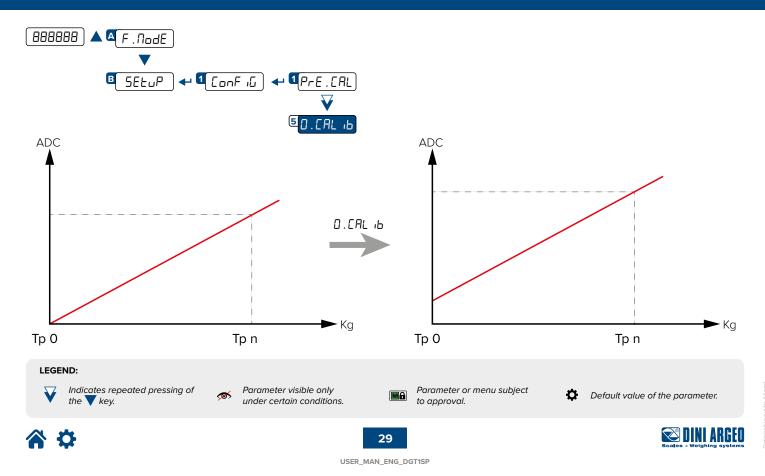
#### **Manual calibration**



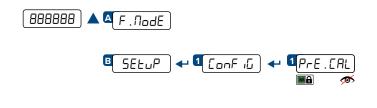
If you know the number of ADC converter points for a known weight (for example if you want to copy the calibration from one transmitter to another) the calibration points can be entered manually:

- **1.** The display shows  $\Pi_{ad}$ .  $P_{\Pi E}$ , and then the last calibration point.
- 2. Using the ▲ and ▼ keys, select the calibration point you want to enter / change (from 0 to 8). Press the ← key to confirm.
- 3. The display shows <code>BE fubble</code>, use the ▲, ▼ and ▶ keys to enter the weight value. Press the ← key to confirm.
- 4. The display shows P<sub>□</sub> mE5, use the ▲, ▼ and ▶ keys to enter the converter points value.
   Press the ← key to confirm.





#### **ADC** converter precalibration

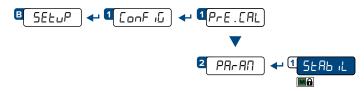


For manufacturer use only

#### **Filter and stability**

#### Filter adjustment





	Filter	Updating frequency (Hz)	Response time (ms)	Use	
	FI	5	5000	High resolution or	
	F 2	10	2500	Oscillating loads	
\$	FΞ	20	1000	Simple weighing	
	FЧ	40	450		
-	FS	80	300	Dosing	
	F 6	160	150		
	F٦	325	50	High-speed weight	
				transmission	

In the case of an approved transmitter, it is possible to select only filter  $F \exists$ .

The filter affects the speed of the PC port only if RLL . TRH mode has been selected.



Ο

Complete menu on pages **24 - 25** 



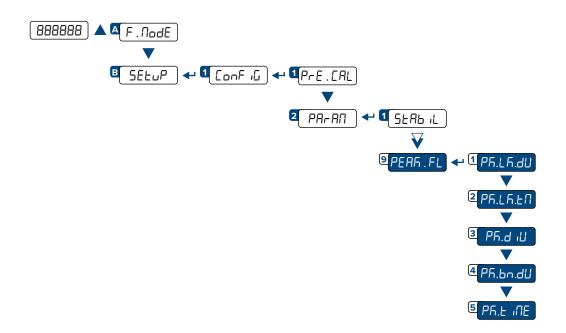
Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the ← key to confirm.



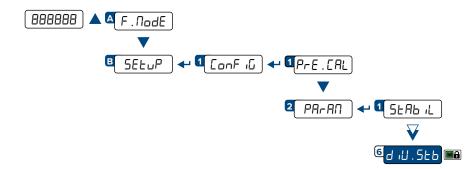
## Anti-peak filter

The transmitter has an additional filter for the elimination of sudden weight peaks (e.g. shocks or falling material). The following parameters, opportunely configured, allow you to eliminate the peak by blocking the weight for its entire duration. The weight is blocked if it remains within the number of divisions set in Ph. Lh. dl for the time set in Ph. Lh. Ln and is subsequently unblocked if the weight deviates from the blocking value for a number of divisions greater than PF. d , J (or PF. bo . dJ) or if the time set in PF. L INE has elapsed.



#### **Stability detection divisions**

It is possible to decide that tare and zero functions (from keypad or serial command / PLC) are performed only if the weight is stable.



From 0 to 99. The value 0 disables the stability control. **O** = 02. By entering a value other than 0, you enable stability control. Enter the number of deviation divisions beyond which the transmitter detects instability. **M** = 02.

the 💙 key.

LEGEND:



Parameter visible only under certain conditions.

Parameter or menu subject to approval.

**Ö** Default value of the parameter.

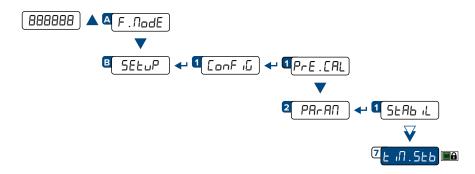


Ø





#### **Stability detection time**

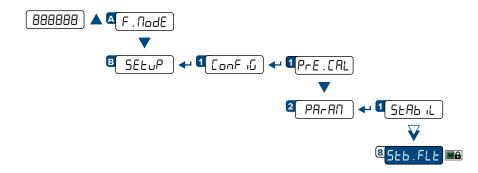


If the weight remains within the number of divisions set in  $d_1U.5b$  for the time set in this parameter, the weight is stable.

Enter the value in ms. In case of approved transmitter, the value is fixed at 500 ms.

from 10 to 10000. 500.

#### Additional filter for stability detection



Additional filter that locks the weight if it oscillates around a value for a maximum of 10 divisions. The weight is unlocked if the value increases/decreases for a time value greater than the time set in this parameter. The value 0 disables the filter.

from 0 to 2000. 0. **\*** = 0.



Complete menu on pages **24 - 25** 





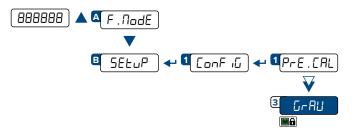
SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUE?. Press the **+** key to confirm.



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#### Gravity



From 9.7500 / to 9.84999.

This parameter allows you to correct the gravity acceleration value. Before calibration, set the value of the calibration zone. Next, set this value to the value of the zone of use. Any difference between the two values will be automatically compensated.

In the case of an approved transmitter, the value is read-only.

#### EXAMPLE:



Calibration zone Italy g = 9.80390

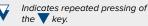


Zone of use Brazil g = 9.77623 **1.** Before calibration, in the  $G \cap RU$  parameter enter the value 9.80390.

2. Calibrate the transmitter.

**3.** Before using the transmitter, in the  $G \cap RU$  parameter enter the value 9.77623.

#### LEGEND:



Parameter visible only under certain conditions.

 $\mathbf{\mathbf{A}}$ 

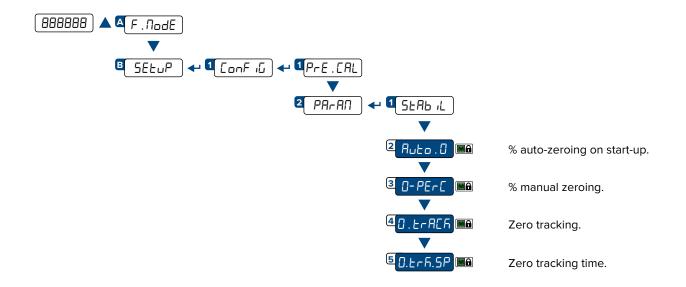
Parameter or menu subject to approval.

Default value of the parameter.





#### **Reset functions and parameters**



#### Auto-zeroing on start-up

2 Ruto.0 🕶 1 d ,5Rb 🌣	Disabled.	
	Enabled, enter in $\mathcal{I}$ . $\mathcal{PE}_{\mathcal{F}}\mathcal{I}$ the % value of the capacity.	from 0 to 50%. from 0 to 10%.

#### Maximum percentage of manual zeroing



Indicates the weight value that can be zeroed by key or command. The value is expressed as % of the full scale. For example: if the scale has a full scale (r AnGE I) of 1000 kg, by setting 3% it is possible to zero up to 30 kg. The value 0 disables the ZERO key and the zeroing commands.

from 0 to 50%. from 0 to 2%. **\$** = 2%.



Complete menu on pages 24 - 25





Press the 🔺 key during the start-

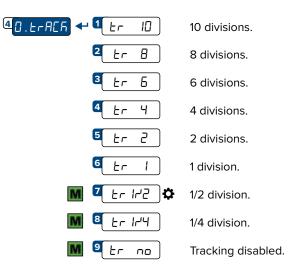
SAVING THE PARAMETERS:

Press the C key several times, until the display shows 



## Zero tracking

This menu allows to set zero tracking, i.e. the compensation parameter of the thermal drift of the scale; the set value corresponds to the number of divisions that is reset to zero in the fixed time of 1 second.



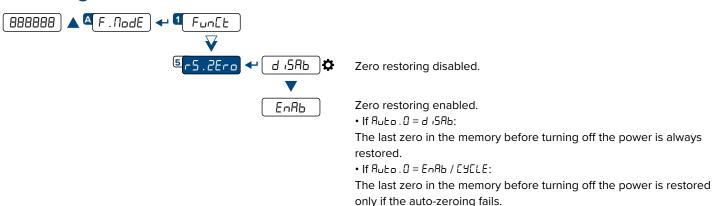
#### Zero tracking time

©0.ErFi.SP ←

Once stability is reached, the transmitter waits for the time set in this parameter before bringing the weight back to zero (if it is within the divisions set in D. ErREF).

from 100 to 5000. 1000.

#### **Restoring zero**



#### Semi-automatic zeroing

By pressing the  $\nabla$  key, or sending the zero command, the transmitter zeroes the gross weight on the scale. For a moment the display shows " $2E_{ro}$ " and then it shows 0 (gross weight).

The semi-automatic zeroing cannot be performed if:

- The weight on the scale is greater than the zero capacity (D. PErC).
- The weight is unstable.



Parameter or menu subject to approval.

Default value of the parameter.

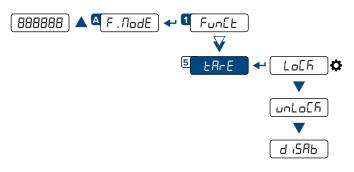


LEGEND:



#### Tare functions and parameters

#### Tare mode



Tare blocked. When the gross weight drops to 0, the tare remains engaged.

Tare unlocked. When the gross weight drops to 0, the tare is cleared.

Tare disabled.

#### Semi-automatic tare

By pressing the  $\blacktriangle$  key, or sending the tare command, the transmitter sets as tare the weight on the scale. For a moment the display shows " $\pounds R_F E$ " and then it shows 0 (net weight). The **3** light indicates that the net weight is shown on the display.

The semi-automatic tare cannot be performed if:

- The weight is less than one division.
- The weight is overloaded.

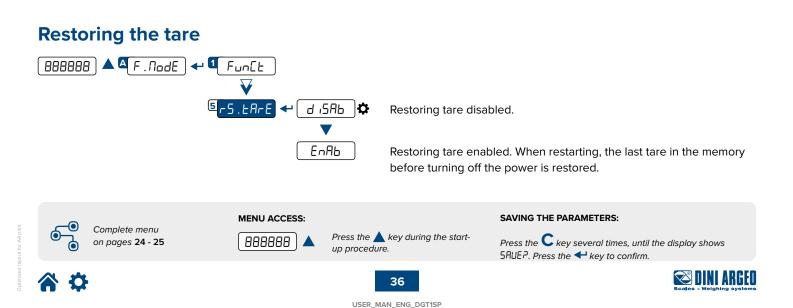
#### **Predetermined tare**

By holding down the  $\blacktriangle$  key, or by means of the predetermined tare command, it is possible to enter a tare value manually. For a moment the display shows "- $t\Pi$ -" and shows the tare present (or 0 if no tare is present). Enter the tare value and press  $\checkmark$  to confirm.

#### **Clearing the tare**

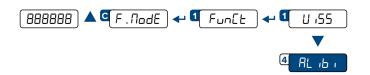
The tare can be cleared in different ways:

- By unloading the scale and performing a semi-automatic tare.
- By entering a predetermined tare value of 0.
- If the weight is negative, pressing the  $\checkmark$  key.



The alibi memory allows you to store the weight values transmitted to the computer for further processing and/or data integration. The stored values can then be retrieved from the PC port or directly on the display of the transmitter for later checking.

# Enabling the alibi memory



# Saving a weighing operation in the alibi memory

A weighing operation is stored after receiving the **PID** serial command (see **"Serial commands" page 57**) or after pressing the **+** key. The transmitter transmits on the PC port the gross weight, the tare and an ID code that uniquely identifies the weighing. The ID has the following format:

• rewrite number: 5-digit number (from 00000 to 00255) indicating the number of complete rewrites;

• weighing number: 6-digit number (from 000000 to 131072) indicating the weighing number in the current rewrite.

Each time it is saved, the weighing number is increased by 1; when it reaches the value 131072, it starts again from 000000 and the rewrite number is increased by 1.

#### Example

If the weighing that has been saved is as follows:

#### PIDST,1, 1.000kg, 1.000kg,00126-131072

The next one will be:

#### PIDST,1, 1.000kg, 1.000kg,00127-000000

A weighing operation can only be saved if the weight  $\geq$  0, stable and valid (not underloaded or overloaded). To store the weighing operation by key, the function must be active (see **"Reactivating printing" on page 53**). In addition, if the transmitter is approved, the weight must exceed 20 divisions.

If these conditions are not met:

• the response to the PID command will have "NO" instead of the ID (PIDST,1, 1.000kg, 1.000kg,NO);

• there is no transmission when the  $\blacktriangleleft$  key is pressed.



Parameter of to approval.





# Reading the alibi memory

#### FROM THE TRANSMITTER (MANUAL)

By pressing the key you can read a saved weight:

you will be asked to enter the rewrite number "rEB. d" (from 0 to 255) and the ID number "d" (from 0 to 131072).

The weighing data are shown. Use the igvee and igwed keys to scroll through the following information:

- " ${\it Lh}$  . X", where X indicates the scale number.
- " $\Pi$  YY", where YY indicates the unit of measurement (FL, L, L or Lb).
- "Gro55", followed by the gross weight.
- "EArE / EArEPE", followed by the tare value.

Press the C key to return to weighing.

The weighing of an ID can only be verified if:

it has a rewrite number equal to the current alibi memory number and a weighing number ≤ the last value received with the PID command;
it has a rewrite number ≥ 0, but 1 less than the current alibi memory value, and a weighing number greater than the last value received with the PID command.

#### FROM PC

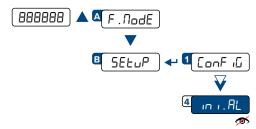
To read a weighing operation from a PC, see the serial command "**READING A WEIGHING OPERATION IN THE ALIBI MEMORY**" on page 57.

#### FROM PLC

To read a weighing operation from a PLC, refer to the Modbus and Fieldbus protocol manuals.

If the alibi memory is empty, when the  $\blacktriangleright$  key is pressed the display shows "Enpty" for one second and returns to weighing mode. If an invalid ID is entered, the display shows "a and returns to weighing mode.

### Initialising the alibi memory



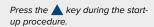
Mot visible if the transmitter is approved.

This operation deletes all saved weighing operations; it is not possible to delete a weighing operation individually.



Complete menu on pages **24 - 25** 



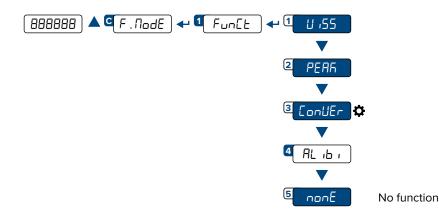


SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the ← key to confirm.



### **Use functions**



### **High resolution**

Weight display in high resolution (x10). Press the  $\triangleright$  key to activate or deactivate the function. When the weight is displayed in high resolution, the 4 light is lit. In the case of an approved transmitter, the high-resolution weight display is automatically deactivated after 5 seconds.

### **Peak detection**

PEAR

U 155

Detection of the maximum weight value during a time interval. Press the key to activate the function. The display shows "- PERF-" every 5 sec and the transmitter shows the maximum weight reached since the function was activated. To deactivate the function press the  $\triangleright$  again, the display shows "PEAGeF" for a moment and shows the instantaneous weight again.

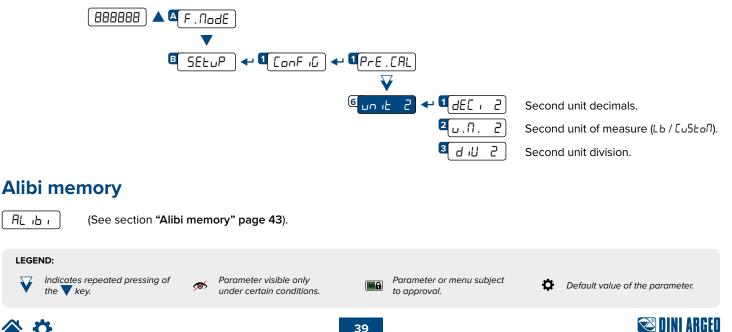
By holding down the 🗲 key it is possible to select in the P 🖞 L 🖉 parameter the minimum time of the pulse duration, expressed in hundredths of a second. The lower this value, the higher the peak function sensitivity.

### **Converting units of measurement**

conUEr

Converting the scale unit of measurement. Press the key to convert the weight to pounds. By holding down the key, you can enter a free conversion factor, which will be multiplied by the weight. Example: To make the instrument convert kg  $\rightarrow$  m<sup>3</sup> of water, enter the value 0.997 as conversion factor. The key can be used to switch from the main unit of measurement to the secondary unit at any time.

When the secondary unit of measurement is displayed, the 4 light is lit. The display of the secondary unit of measure can be configured in the parameter un ال 2:





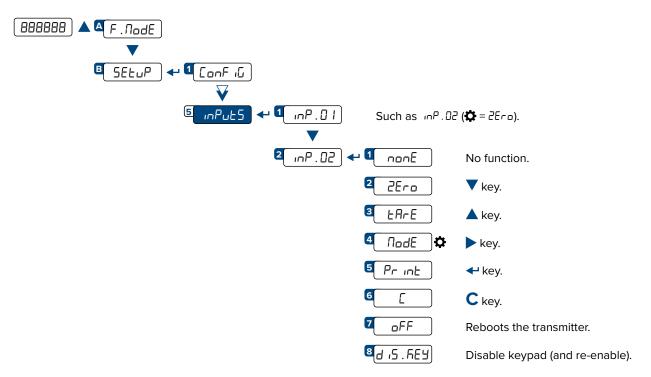
AL њ

LEGEND:

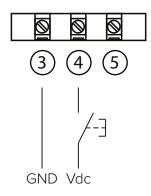


# Input configuration

The indicator has 2 configurable inputs (bidirectional optocouplers).



#### INPUT CONNECTION:



The input is activated when there is a potential difference between terminals 4 - 5 (IN1 and IN2) and terminal 3 (INCOM). The inputs are bidirectional, therefore it is possible to invert GND and Vdc.



Complete menu on pages 24 - 25



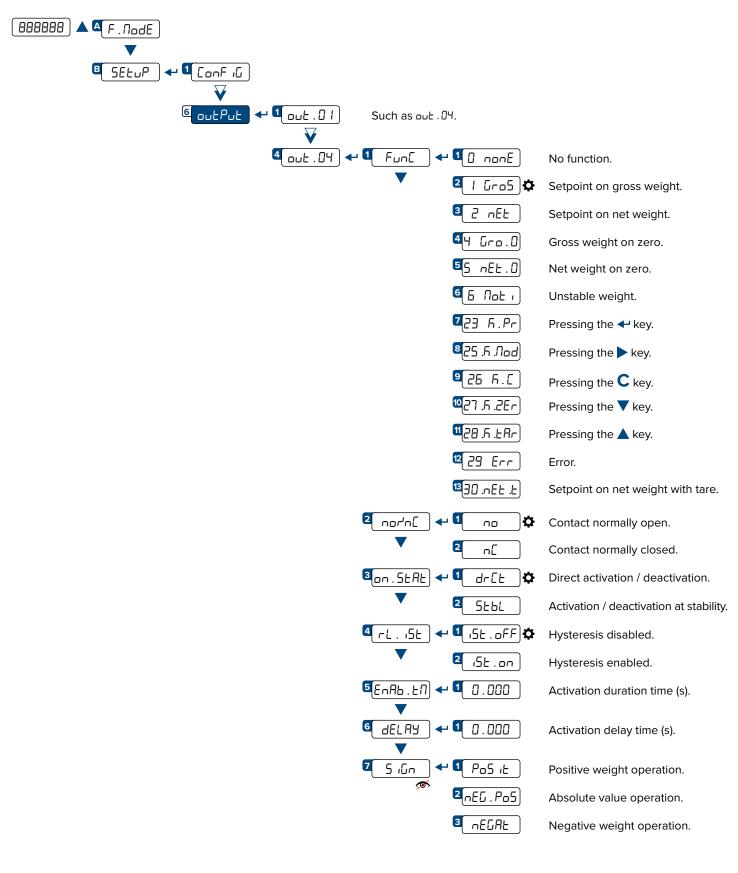
Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUE?. Press the **↔** key to confirm.



### **Output configuration**

The indicator has 2 programmable outputs (photomosfet).



#### LEGEND:

Indicates repeated pressing of the key.

Parameter visible only under certain conditions. Parameter or menu subject to approval.

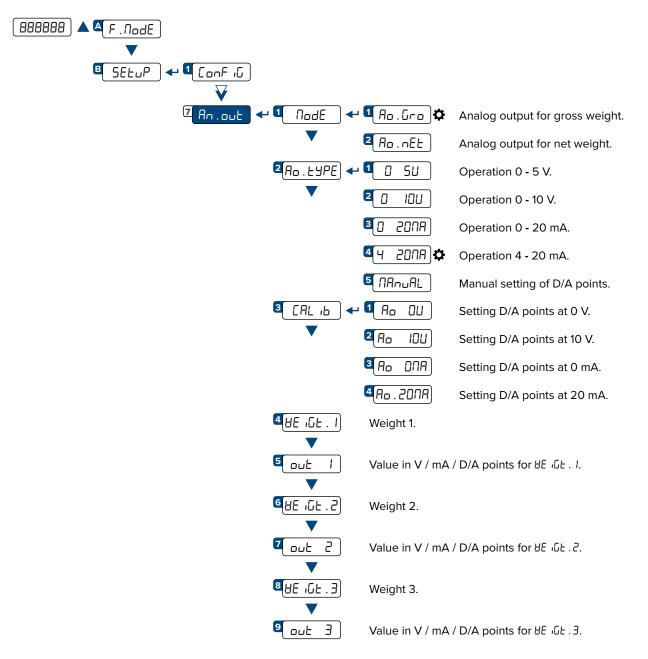
Default value of the parameter.







The DGT1SP-AN model has an analog output in voltage (0 - 5 / 0 - 10 Vdc) or current (4 - 20 / 0 - 20 mA).



This menu allows an advanced configuration of the analog output.

For simple configurations, it is recommended to use the quick menu (Ref. Quick Start Guide).



Complete menu on pages **24 - 25** 



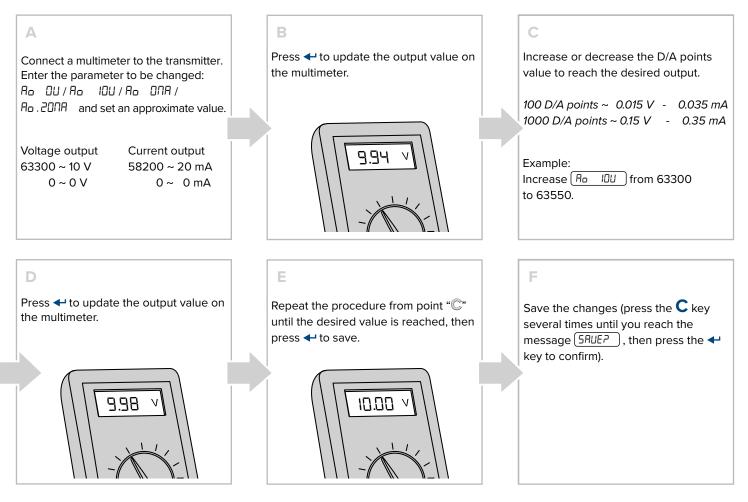
Press the 🛕 key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUE?. Press the **↔** key to confirm.

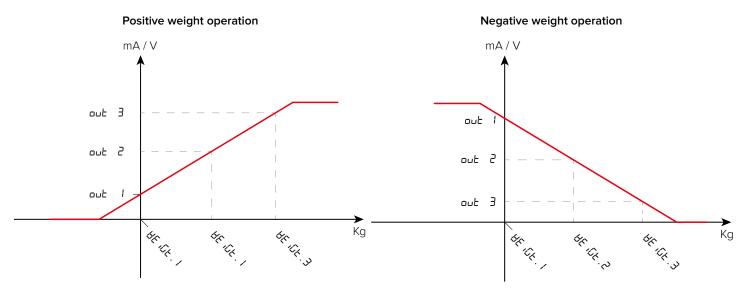


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#### CALIBRATION PROCEDURE:



#### ANALOG OUTPUT GRAPHS:



,\_\_\_\_\_

Voltage or current operation is determined by the connection to the transmitter terminals:

<u>Current:</u> 9 (+) and 10 (-). <u>Voltage:</u> 11 (+) and 12 (-).

#### LEGEND:

Indicates repeated pressing of the key.

Parameter visible only under certain conditions. Parameter or menu subject to approval.

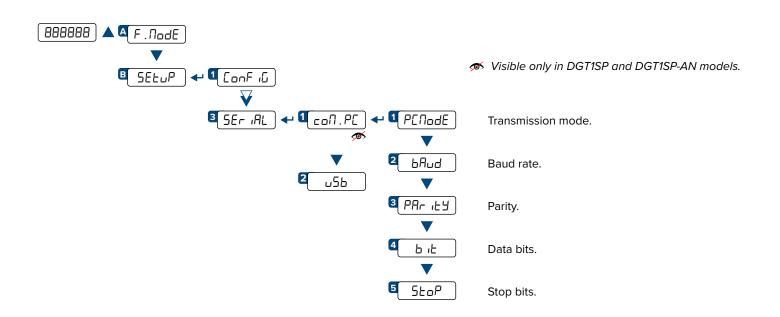
Default value of the parameter.

🛎 DINI ARGEO

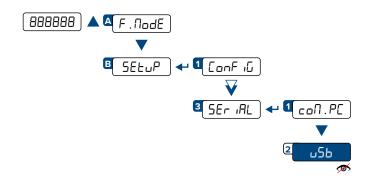




All models are equipped with a micro-USB port that is always accessible for transmitter configuration and diagnostics. The DGT1SP and DGT1SP-AN models also have an RS485 port.



# Configuration of the USB port



Useful for the configuration of the instrument from PC with Dinitools.



Complete menu on pages 24 - 25



Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUE?. Press the **+** key to confirm.



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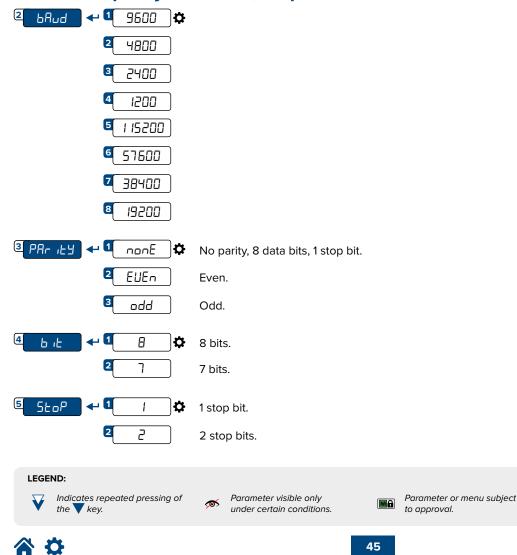
# Configuration of the 485 port (PC port)

# **Transmission mode**

I PENodE ← I ondE	Transmission on demand.
<b>2 - EPE</b> . <b>6</b>	Transmission of the weight on DINI ARGEO 6-digit repeater.
🔹 🕄 Pr. in . 5E	Standard string transmission when the <table-cell-rows> key is pressed.</table-cell-rows>
\star 4Pr. in.EH	Extended string transmission when the $\blacktriangleleft$ key is pressed.
5 485	Transmission with 485 protocol (enter the 485 address of the transmitter).
6 Nodbu5 🗘	Transmission with Modbus protocol (refer to the Modbus protocol manual).
ZALL . NAH	Continuous high speed weight transmission for conversion applications (single channel only)
🔹 🛿 🔒 😣 😵	Continuous transmission of the standard string (select the transmission frequency, about 1 $\div$ 80 Hz).
🔹 🛛 🖓 RLL.EHE	Continuous transmission of the extended string (select the transmission frequency, about 1 $\div$ 80 Hz).
😻 🔨 SERB.SE	Stable transmission of the standard string.
😻 🏛 SERb.EH	Stable transmission of the extended string.
*	

When selecting one of these protocols, you are asked if you want to display the 485 address at the beginning of the string: dEU. Id + YE5 / no.

### Baud rate, parity, data bits, stop bits





Default value of the parameter.

# **Standard string**

### [01]ST,GS, 0.0,kg<CR><LF>

Where:	
01	Transmitter code 485 (2 characters), only if communication mode 485 is enabled
ST	Scale status <i>(2 characters):</i> <u>US</u> - Unstable weight <u>ST</u> - Stable weight <u>OL</u> - Weight overload <i>(out of range)</i> <u>UL</u> - Weight underload <i>(out of range)</i>
,	Character ASCII 044
GS	Type of weight data <i>(2 characters)</i> <u>GS</u> - Gross <u>NT</u> - Net <u>VL</u> - Microvolts <u>RZ</u> - Converter points
,	Character ASCII 044
0.0	Weight (8 characters including the decimal point)
,	Character ASCII 044
kg	Unit of measurement (2 characters)
<cr><lf></lf></cr>	Transmission terminator, characters ASCII 013 and ASCII 010

# **Extended string**

<b>[01]1ST,1,</b> Where:	0.0,PT	20.8,	0,kg,01/02/19 11:12:13 <cr><lf></lf></cr>
01		Transmitter c	ode 485 (2 characters), only if communication mode 485 is enabled
1		Number of th	ne active scale
ST		<u>US</u> - Unstable <u>ST</u> - Stable w <u>OL</u> - Weight e	5
,		Character AS	SCII 044
0.0		Weight (8 ch	aracters including the decimal point)
,		Character AS	SCII 044
PT		Preset tare ir	ndication
20.8		Tare (8 charc	acters including the decimal point)
,		Character AS	SCII 044
0		Character AS	SCII 048
,		Character AS	SCII 044
kg		Unit of meas	urement (2 characters)
,		Character AS	SCII 044
01/02/19 11:	:12:13	dd/mm/yy hl	h:mm:ss (only with REXD command and optional clock card)
<cr><lf></lf></cr>		Transmission	terminator, characters ASCII 013 and ASCII 010







# Serial commands

By selecting the PC port on demand mode (andE), you can communicate with the transmitter via serial commands. For each command received, the transmitter emits a string containing the response (refer to the command description) or one of the following signals:

OK <crlf></crlf>	Command sent when sending a correct command. This response does not imply that the command is executed.
ERR01 <crlf></crlf>	Command sent correctly but followed by letters entered unintentionally (e.g. READF, TARES).
ERR02 <crlf></crlf>	Incorrect command data.
ERR03 <crlf></crlf>	Command sent not allowed (transmitter busy, or not used in the selected operating mode).
ERR04 <crlf></crlf>	Command sent non-existent.

If the 485 protocol has been selected, you must precede the command with the transmitter address (e.g. 01READ).

#### WEIGHT READING (standard string)

Format	R	Е	А	D	<cr lf=""></cr>
Response	Star	ndard	strin	ig <c⊮< th=""><th>R LF&gt;.</th></c⊮<>	R LF>.

#### WEIGHT READING IN HIGH RESOLUTION (X10)

Format	G	R	1	0	<cr lf=""></cr>	
Response	Stan	dard	string	with v	veight in res	olution x10 <cr lf="">.</cr>

#### MANUAL TARE

Format	Т	М	А	Ν	t	t	t	t	t	t
	<cr< th=""><th>LF&gt;</th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th></cr<>	LF>								
Where		tttttt				tar	e val	ue		
Response	OK<	CR L	F> (o	r ERF	Rxx).					

By entering a manual tare value of 0, the tare on the scale is cleared.

#### DISABLING KEYPAD

Format	К	Е	Y	Е	D	<cr lf=""></cr>	
Response	OK<	CR L	.F> <b>(o</b>	r ERF	Rxx).		

#### **READING INPUTS**

Format	I	Ν	Р	U	n	<cr< th=""><th>LF&gt;</th><th>]</th><th></th></cr<>	LF>	]		
Where	n		nput	(1 / 2)				-		
Response	I	Ν	Р	U	n	v	v	v	v	
	<cr< th=""><th>LF&gt;</th><th></th><th></th><th></th><th></th><th></th><th></th><th></th></cr<>	LF>								
	ı	n	Inpu	ıt nur	nber.					
			Input status:							
Where	vv	vv	000	)0 = N )1 = A F = In	ctive	•		ror.		

#### EXTENDED WEIGHT READING

Format	R	E	x	Т	<cr lf=""></cr>
Response	Exte	endeo	d strii	ng <c< th=""><th>R LF&gt;.</th></c<>	R LF>.

#### AUTOMATIC TARE

Format	Т	А	R	Е	[I]	<cr lf=""></cr>	]
Response	OK<	CR L	.F> <b>(o</b>	r ERF	Rxx).		

Send the TAREI command to perform tare without stability control.

#### ZEROING

Format	Z	Е	R	0	[I]	<cr lf=""></cr>	
Response	OK<	CR L	.F> <b>(</b> 0	r ERF	Rxx).		

Send the ZEROI command to perform zeroing without stability control.

#### ENABLING KEYPAD

Format	К	Е	Y	Е	Е	<cr lf=""></cr>	
Response	OK<	CR L	.F> <b>(o</b>	r ERF	Rxx).		

#### **READING OUTPUTS**

Format	0	U	Т	S	n	<cr< th=""><th>LF&gt;</th><th>]</th><th></th></cr<>	LF>	]				
Where	n	0	utpu	t (1 / 4	1).			-				
Response	0	U	Т	S	n	v	v	v	v			
	<cr< th=""><th>LF&gt;</th><th></th><th></th><th></th><th></th><th></th><th></th><th></th></cr<>	LF>										
	n Output number.											
			Out	put s	tatus	:						
Where	vv	vvvv 0000 = Not active. 0001 = Active. FFFF = Output reading error.										





#### PRESSING A KEY

Format	К	E	Y	Р	х	х	<cr lf=""></cr>
	х	х		Key o	code.		
	0	0			7		
	C	)1					
Where	0	2					
	0	3			μ		
	0	4		C			
						-	
Response	OK⊲	<cr l<="" th=""><th>.F&gt; (o</th><th>r ERF</th><th></th><th></th></cr>	.F> (o	r ERF			

#### **RELEASING A KEY**

Format	К	Е	Y	R	<cr lf=""></cr>
Response	OK<	CR L	.F> <b>(o</b>	r ERF	₹xx).

### SCALE INFORMATION

SCALE INFORM							,																
Format	R	А	L	L	<cr< th=""><th>LF&gt;</th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th></cr<>	LF>																	
	S	s	,	b	,	Ν	Ν	Ν	Ν	Ν	Ν	u	u	,	L	L	L	L	L	L	u	u	,
Response	Y	Y	Т	Т	Т	Т	Т	Т	u	u	,	S	S	S	,	А	А	Α	,	С	С	С	С
	,	,	R	R	R	R	R	-	Ι	Ι	Ι	Ι	Ι	Ι	<cr< th=""><th>LF&gt;</th><th></th><th></th><th></th><th></th><th></th><th></th><th></th></cr<>	LF>							
		SS		OL = ST =	= Unc = Ove = Stat = Uns	erload ole w	d. eight																
		b		Nun	nber	of the	e acti	ve so	ale.														
	NNI	NNNI	Nuu	Net	weig	ht wi	th un	it of	meas	urem	ent.												
	LL	LLLL	uu	Gro	ss we	eight	with	unit d	of me	asure	emen	t.											
		ΥY		PT i	PT if a manual tare is present or "".																		
	TT	тттт	uu	Tare	Tare with unit of measurement.																		
Where		SSS		000 001	Tare with unit of measurement. Scale status: 000 = scale weighing. 001 = entering a numerical value. 002 = scale in technical menu.																		
		ΑΑΑ		000 000 000	Counter keys pressed: $0001 = \bigvee$ $0002 = \triangle$ $0003 = \triangleright$ $0004 = \checkmark$ $0170 = \bigcirc$																		
	(	ccco	2	Code of last key pressed.																			
	F	RRR	R	Last rewrite number saved to Alibi memory.																			
				Last	: ID n	umbe	er sav	/ed to	o Alib	i me	mory												

To simulate pressing a key, you must send the KEYP and KEYR commands in succession. If more than 1.5 s pass after the KEYP command is sent, the transmitter will execute the function associated with prolonged pressing of the key.

#### **BRIDGE BETWEEN THE SERIAL PORTS**

Format	В	R	I	D	G	Е	1	<cr lf=""></cr>
Response	OK<	CR L	.F> (o	r ERF	Rxx).			



#### **READING OF MICROVOLTS**

Format	М	V	0	L	
Response	Star	ndard	l strin	ig <c⊦< th=""><th>RLF&gt;.</th></c⊦<>	RLF>.

### INITIALISING ALIBI MEMORY

Format	А	L	D	L
Response	ALD	LOK	/ AL[	DLNC

### READING OF CONVERTER POINTS

Format	R	А	Ζ	F	]			
Response	Star	ndard	strin	i <b>g</b> <c⊦< th=""><th>R LF&gt;</th><th></th><th></th><th></th></c⊦<>	R LF>			

#### WEIGHT READING WITH DATE AND TIME

Format	R	Е	Х	D	
Response	Exte	endeo	d strir	ng <c< th=""><th>R LF&gt;.</th></c<>	R LF>.

#### READING A WEIGHING OPERATION IN THE ALIBI MEMORY

Format	А	L	R	D	Х	Х	Х	Х	Х	-	Y	Y	Y	Y	Y	Y	<cr lf=""></cr>			
	b	,	L	L	L	L	L	L	L	L	L	L	u	u	,					
Response	Y	Y	Т	Т	Т	Т	Т	Т	Т	Т	Т	Т	u	u	<cr< td=""><td>LF&gt;</td><td></td><td></td><td></td><td></td></cr<>	LF>				
		ł	b		Sca	cale number.														
14/1	LL	LLLL	LLLL	uu	Gro	Gross weight with unit of measurement.														
Where		Y	Ϋ́		"PT if a manual tare is present or " ".															
	ТТ	тттт	TTT	Tuu	Tare with unit of measurement.															

#### SAVING A WEIGHING OPERATION IN THE ALIBI MEMORY

Format	Р	Ι	D	<cr< th=""><th>LF&gt;</th><th>]</th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th><th></th></cr<>	LF>	]																	
	Р	I	D	s	Т	,	b	,	L	L	L	L	L	L	L	L	L	L	u	u	,	Y	Y
Response	Т	Т	Т	Т	Т	Т	Т	Т	Т	Т	u	u	,	x	Х	Х	X	Х	-	Y	Y	Y	Y
	Y	Y	<cr< td=""><td>LF&gt;</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></cr<>	LF>																			
		ł	b		Sca	Scale number.																	
	LL	LLLL	LLLL	uu	Gro	Gross weight with unit of measurement.																	
Where		Y	Υ		"PT	if a n	nanua	al tar	e is p	rese	nt or	"".											
where	ТТ	тттт	TTTT	Tuu	"PT if a manual tare is present or "". Tare with unit of measurement.																		
		XXX	XXX		Rewrite number.																		
		YYY	YYY		ID number.																		

11)—

The fieldbus protocol is described in the respective manual.





# **Modbus Protocol**

### MODBUS REGISTERS FOR DATA READING (SINGLE SCALE)

Data	Register	DESCRIPTION		
Gross Weight	30001	Gross weight value.		
	30002			
Net Weight	30003	Net weight value		
Net Weight	30004	Net weight value.		
Input status register	30005	Bit 15 (msb)Active channel.Bit 14 Bit 13Active channel.Bit 13No function.Bit 12No function.Bit 12No function.Bit 14No function.Bit 15Input no. 2 status.Bit 7 (msb)Gross zero zone (0 = "outside zone 0"; 1 = "in zone 0").Bit 6Tare PT (1 = a preset tare is active).Bit 5Tare (1 = a tare is active).Bit 4Overload condition (0 = No; 1 = Overload).Bit 3Underload condition (0 = No; 1 = Underload).Bit 4Stability (0 = Unstable; 1 = Stable).Bit 1Gross weight sign (0 = "+"; 1 = "-").Bit 0 		
Command status register	30006	Last command received.         Bit 7 <sub>(msb)</sub> Last command result.         Last command result.         Last command result.         Bit 5       Last command result.         Bit 4       Last command result.         Bit 3       Processed command count.         Bit 2       Processed command count.         Bit 1       Processed command count.         Bit 0       Processed command count.		
Output status register	30007	No function.         Bit 7 <sub>(msb)</sub> No function.            Bit 2         No function.         Bit 1         Digital output 1 status (0 = OFF; 1 = ON).         Bit 0 <sub>(lsb)</sub> Digital output 2 status (0 = OFF; 1 = ON).		
μV Channel 1	30111	μV value.		

This manual contains the main registers for reading data / sending commands. Refer to the Modbus protocol manual for a complete list of available registers.

**A Q** 



#### MODBUS REGISTERS FOR SENDING COMMANDS

Data	Register	DESCRIPTION		
			mands available:	
		Value	Command	
		00 Hex	No command	
		01 Hex	Zero	
	40001	02 Hex	Tare	
Command		03 Hex	Predetermined tare	
		0A Hex	Setting setpoint 1	
		0B Hex	Setting setpoint 2	
		19 Hex	Setting digital outputs	
		22 Hex	Rebooting the transmitter	
Parameter 1	40002	First command parameter.		
	40003	The parameter is always expressed as an absolute value (no decimal / sign).		
Parameter 2	40004	Second command parameter. The parameter is always expressed as an absolute value (no decimal / sign).		
	40005			

#### EXAMPLE 1

To reset the weight on the scale:

2. Set the command in register 40001

Byte	Value
1	00 Hex
2	01 Hex

#### EXAMPLE 2

To set a predetermined tare of 1000kg:

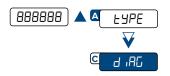
Set the value in parameter 1 (registers 40002-40003)
 Set the command in register 40001

Byte	Value
1	00 Hex
2	03 Hex
3 <sub>(MSB)</sub>	00 Hex
4	00 Hex
5	03 Hex
6 <sub>(LSB)</sub>	E8 Hex

This manual contains the main registers for reading data / sending commands. Refer to the Modbus protocol manual for a complete list of available registers.



### Diagnostics



# Cells / converter test



Display of the  $\mu$ V related to the weight on the scale.

For correct operation, the value of the  $\mu$ V of each channel must be less than 30000 with a weight equal to the maximum capacity. This value must be stable, and increase if a load is applied to the cell.



Display of the A/D points of the converter related to the weight on the scale.

For correct operation, the value of A/D points must be stable, and increase if a load is applied to the cell.

### **Firmware release**

1 PrG.UEr

Display of firmware release (e.g. 0 1.06.00).

### Serial number

<sup>15</sup>5Ег.пиП Display of transmitter serial number.

### Display

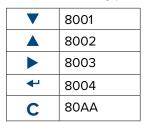


Activation of all display segments and indicators.

# Keypad



The code of last key pressed is shown on the display:



Press the same key 3 consecutive times to exit.



Complete menu on pages **24 - 25** 



Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the **4** key to confirm.



# Serial ports



Bridge between serial ports (for manufacturer's use).

# Inputs

13 inPut5 Checking the status of the inputs: value 0 indicates that the input is disabled, value 1 indicates that the input is enabled. Use the  $\blacktriangle$  and  $\bigtriangledown$  keys to display the two inputs.

### **Outputs**

12 outPut

🕰 An . out

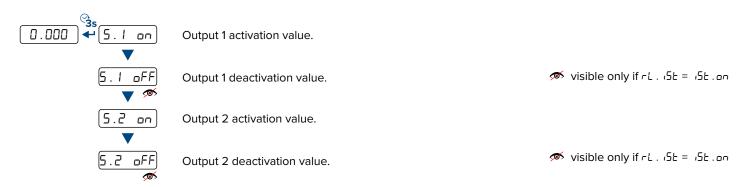
Activation of the output shown on the display (rEL . 1/rEL . 2). Use the  $\blacktriangle$  and  $\bigtriangledown$  keys to activate the two outputs.

# Analog output (mod. DGT1SP-AN)

Analog output test. Use the  $\blacktriangle$ ,  $\nabla$ ,  $\triangleright$  keys to enter the D/A point value of the analog output. Press the - key to confirm and update the V / mA value of the analog output.

# **Programming the Setpoints**

In weighing mode, if the output functions ( / 🖸 🕫 5 / 2 🕫 Et) have been set correctly, pressing 🗲 for 3 seconds will enter the setpoint programming menu:



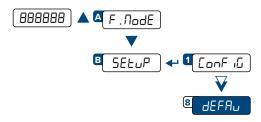
Once you have entered the desired values, press C. The display shows "5LorE" and returns to weighing mode.







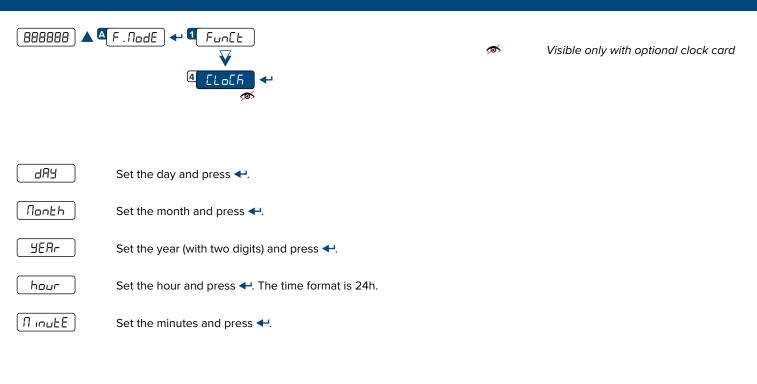
### **Restoring factory settings**



The transmitter is initialized and the default parameters (indicated by the  $\clubsuit$  symbol) are activated. Pressing  $\checkmark$  the display shows "*dFLEr*" confirm further with  $\checkmark$  or exit by pressing another key.

The actual activation of the default parameters is performed by saving the settings (SRUEP) while exiting the menu.

### Date and time setting



The date and time format is: DD/MM/YY, HH:MM:SS (24h),



Complete menu on pages **24 - 25** 



Press the key during the startup procedure. SAVING THE PARAMETERS:

Press the **C** key several times, until the display shows SRUEP. Press the ← key to confirm.



### Alarms

PrEE       Displayed if you try to calibrate a point without first confirming the number of calibration point acquisition.         Er .flot       Calibration error: unstable weight during point acquisition.	points (p. $EP$ )		
Er . Not Calibration error: unstable weight during point acquisition.	Displayed if you try to calibrate a point without first confirming the number of calibration points ( $n E^{P}$ ).		
	Calibration error: unstable weight during point acquisition.		
ErPnt Calibration error: during the acquisition of a calibration point a NULL value was read from	Calibration error: during the acquisition of a calibration point a NULL value was read from the converter.		
Error that occurs if the capacity of channel <i>H</i> is not set, or there is an error in the calibratic channel <i>H</i> , where <i>H</i> indicates the number of the channel to which the error refers.	Error that occurs if the capacity of channel <i>H</i> is not set, or there is an error in the calibration parameters of channel <i>H</i> , where <i>H</i> indicates the number of the channel to which the error refers.		
Error that occurs if the capacity of channel <i>H</i> is not set, or there is an error in the calibratic channel <i>H</i> , where <i>H</i> indicates the number of the channel to which the error refers.	Error that occurs if the capacity of channel <i>H</i> is not set, or there is an error in the calibration parameters of channel <i>H</i> , where <i>H</i> indicates the number of the channel to which the error refers.		
Er II Calibration error: a sample weight that is too low was used; it is recommended to use a w the scale's capacity.	reight of at least half		
Er 12 Calibration error: The acquired calibration point (EP 1/EP 2/EP 3) is equal to the zero point	int (£ <i>P0</i> ).		
$E_r \exists \gamma$ Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEF proceeding).	R⊔" settings before		
$E_r$ 39 Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEF proceeding).	Scale to be calibrated (we recommend resetting the transmitter to the factory default "dEFAu" settings before proceeding).		
L.Er35Negative internal points were calculated during calibration: • the calibration point is below the zero point; • the signal is negative (check the connections).	Negative internal points were calculated during calibration:         • the calibration point is below the zero point;		
L.Er37Internal points below the minimum value were calculated during calibration: • the calibration point is equal to the zero point; • too high a capacity has been set with respect to the division.	the calibration point is equal to the zero point;		
Hardware error: software not compatible with the installed hardware.	Hardware error: software not compatible with the installed hardware.		
	Displayed when the alibi memory is enabled and the transmitter does not detect the presence of the card when the power is turned on. The $L_{aa}U$ function is set automatically, but not saved in the setup environment.		
bu5년 Printing in progress (printer serial port busy) or transmitter waiting to transmit a print to PC	Printing in progress (printer serial port busy) or transmitter waiting to transmit a print to PC.		
You are trying to print with an unstable weight.	You are trying to print with an unstable weight.		
un . ولالات You are trying to print with the weight in underload / overload.	You are trying to print with the weight in underload / overload.		
The weight is overloaded (9 divisions over the maximum capacity).			
The weight is underloaded.			
Image: Second strain	visions.		
<i>ν</i> Ε <i>τ</i> . <i>Eττ</i> You are trying to print with a non-positive net weight (less than or equal to zero).			
me. D. un5 Weight not passed by net 0 or instability.			
Lonu         You are trying to print while the transmitter is converting the unit of measurement.			
Err. ELF Communication problems with the clock card of the transmitter.			
EEL.Err     Signal anomaly: check the connection of the cells.	Signal anomaly: check the connection of the cells.		



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Parameter or menu subject to approval.



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**Notes** 






Notes







**Notes** 







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